1.Preparation

This course is mainly based on the accelerometer that comes with micro:bit.

When we rotate the micro:bit around the x-axis, that is, when rotating on the yoz plane, the degree of the rotation (picth) will be changed.

When we rotate the micro:bit around the y-axis, that is, when rotating on the xoz plane, the degree of the rotation (roll) will be changed.

When we rotate the micro:bit around the z-axis, that is, when rotating on the yoz plane, the degree of the rotation (yaw) will be changed.

In this experiment, we use the rotation angle to judge.

Programming method:

Mode 1 online programming: First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: http://microbit.org/ to enter the programming interface. Add the Yahboom package: http://microbit.org/ to enter the programming

Mode 2 offline programming: We need to open the offline programming software. After the installation is complete, enter the programming interface, click [New Project], add Yahboom package: https://github.com/lzty634158/Tiny-bit, you can program.

In the picture shown below, the ultrasonic module with red wire frame.

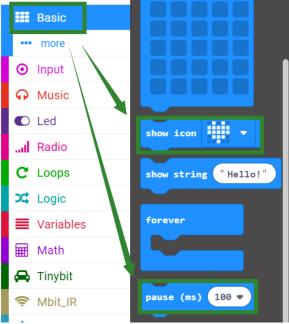
2.Learning goal

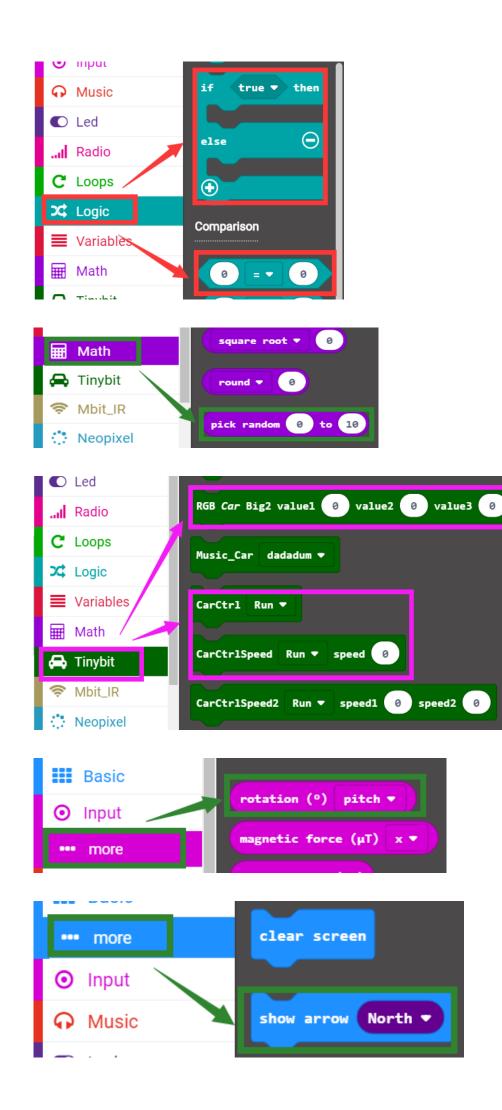
2-1. Learn how to use accelerometer graphically program building blocks

2-2. The function is realized by programming: when we gently press the tail of the robot car with our hand, the Tiny-bit will make a sound and advance a short distance.

3.Search for block

The following is the location of the building blocks required for this programming.







4.Combine block

The summary program is shown below:

f rota	tion (°)	pitch			-15	then	she	w led	s	-							
show arrow	South 🔻)	- +	+	+	+ +											
start melod	y jump u	p 🔹 r	epeatin	gonc	:e 🔻												
CarCtr1Spee	d Run 🔻	speed	75	+	+												
pause (ms)	500 💌	+															
CarCtrl St	op 🔻						Car	•Ctrl	Stop 🔻								
show icon	8.1	+								+							
Ð																	
	+																
rever	+																
if rota	tion (°)	pitch	•	< 🕶 (-15	then	+										
RGB Car Big	2 value1	pick	random	0	to 25	5 valu	e2 pic	rand	om 0	to 25	55 V	alue3	pick	rando	om Ø	to	2!

5.Experimental phenomena

After the program download is complete, open the power of the robot car. When we gently press the tail of the Tiny-bit, the forward arrow will be displayed on the micro:bit dot matrix, and a piece of music will be played, and the lights will be randomly lit at the same time, the car advances for a short time, then stops.

As shown below.

